8 7 5 4 NOTES: DRAWING APLLIES TO THE FOLLOWING SMARTMOTOR WITH PART NUMBERS: 1. SM34165D-BRK-C-AD1 SM34165D-DEBRK-C-AD1 SM34165D-BRKSH-C-AD1 SM34165D-DEBRKSH-C-AD1 LED, SERVO-AMPLIFIER: 2. CLEAR = CONTROLLER POWER NOT AVAILABLE RED = FAULTFLASH GREEN = DRIVE (AMPLIFIER) IS OFF F GREEN = DRIVE (AMPLIFIER) IS ON LED, TRAJECTORY CLEAR = NOT IN CONTROLLED TRAJECTORY (DEFAULT STATE) GREEN = IN CONTROLLED TRAJECTORY (CLOSE LOOP MOTION) LED, CANopen ERROR LED (RED) 3. CLEAR = NO ERRORSINGLE FLASH = WARNING, COMMUNICATION ERROR COUNT LIMIT REACHED DOUBLE FLASH = GUARD OR HEART BEAT ERROR CANopen RUN LED (GREEN) SINGLE FLASH = DEVICE IS IN STOPPED STATE BLINKING = PREOPERATIONAL STATE SOLID = OPERATIONAL STATE FOR -DE OPTION, DRIVE POWER AND CONTROLLER POWER ARE ON SEPARATE 4. PINS. MUST PROVIDE POWER TO CONTROLLER AND DRIVE POWER TO OPERATE. SEE TABLE CN2 BELOW FOR PIN ASSIGNMENT. Е DIMENSIONS IN [] ARE mm. 5. RECOMMENDED BOLTING SCREW SIZE TO BE 10-32 OR M5, SOCKET CAP. 6. D Ø2.875±.002 [73.03±0.05] 4X Ø.203 [5.15] THRU ON Ø3.875 [98.43] B.C. EQUALLY SPACED O O Ø.3745±.0003 9.512±0.008 4.16 105.7 С ()3.40 [86.3] 0 \bigcirc 3.40 [86.4] 1.17 29.7 -DETAIL A SCALE 1.5 : 1 15 CN2: 15PIN D-SUB FEMALE CONNECTOR FUNCTIONS PIN # NAME Default Function Secondary Function Digital I/O Analog Input I/O A External Encoder A Input Step Input 5V TTL 0 to 5V 1 I/O B 5V TTL 2 External Encoder B Input Direction Input 0 to 5V I/O C 3 5V TTL 0 to 5V Positive Limit Input

4	I/O D	Negative Limit Input		5V TTL	0 to 5V					
5	I/O E		RS485 A (Pos)	5V TTL	0 to 5V					
6	I/O F		R5485 B (Neg) 5V TTL 0 to 5V			CN1: 7PIN COMBO D-Sub Male Connector				CONFIDENTIAL. THE
7	I/O G	G-Synchronization	RS485-ISO Adopter Data	5V TTL	0 to 5V	DTNI #	NAME	FUNCTIONS	Ties to CN2,	AND IS PROTECTED A
8	ENC A OUT	Encoder A Output				FIN #	NAME	TONCTIONS	PIN #	INFORMATION CONFIL MATERIAL
9	ENC B OUT	Encoder B Output				1	I/OG	G-Synchronization	7	
10	R5232 Tx	RS232 Transmit				2	+5V dc OUT	+5Vdc Output	12	HOUSING
11	R5232 Rx	RS232 Receive				3	R5232 Tx	RS232 Transmit	10	INCH U
12	+5Vdc OUT	+5Vdc Supply Out				4	R5232 Rx	RS232 Received	11	THIRD ANGLE
13	GND	Signal GND				5	GND	Signal GND	13	PROJECTION
14	POWER GND	POWER GND	For -DE Option, Pin 15 is Contorl power (20V to 48V) and			A1	DRIVE PWR	Dirve Power (20 - 48Vdc)	15^	
15	POWER	POWER	Pin 14 is PWR GND. ^PIN 15 is not connected to A1.			A2	POWER GND	POWER GND	14	
	8		7		6			5	A	4
	11 12 13 14	5 I/O E 6 I/O F 7 I/O G 8 ENC A OUT 9 ENC B OUT 10 RS232 Tx 11 RS232 Rx 12 +5Vdc OUT 13 GND 14 POWER GND	5I/O E6I/O F7I/O G8ENC A OUT9ENC B OUT10RS232 TxRS232 TxRS232 Transmit11RS232 RxRS232 RxRS232 Receive12+5Vdc OUT+5Vdc OUTSignal GND14POWER GND	5I/O ERS485 A (Pos)6I/O FRS485 B (Neg)7I/O GG-SynchronizationRS485-ISO Adopter Data8ENC A OUTEncoder A Output9ENC B OUTEncoder B Output10RS232 TxRS232 Transmit11RS232 RxRS232 Receive12+5Vdc OUT+5Vdc Supply Out13GNDSignal GND14POWER GNDFor -DE Option, Pin 15 is Cor	5I/O ERS485 A (Pos)5V TTL6I/O FRS485 B (Neg)5V TTL7I/O GG-SynchronizationRS485-ISO Adopter Data5V TTL8ENC A OUTEncoder A Output9ENC B OUTEncoder B Output9ENC B OUTEncoder B Output10RS232 TxRS232 Transmit11RS232 RxRS232 Receive12+5Vdc OUT+5Vdc Supply Out13GNDSignal GNDFor -DE Option, Pin 15 is Contorl power (20V	5I/O ERS485 A (Pos)5V TTL0 to 5V6I/O FRS485 B (Neg)5V TTL0 to 5V7I/O GG-SynchronizationRS485-ISO Adopter Data5V TTL0 to 5V8ENC A OUTEncoder A Output9ENC B OUTEncoder B Output10RS232 TxRS232 Transmit11RS232 RxRS232 Receive12+5Vdc OUT+5Vdc Supply Out13GNDSignal GND14POWER GNDFor -DE Option, Pin 15 is Contorl power (20V to 48V) and	5I/O ERS485 A (Pos)5V TTL0 to 5V6I/O FRS485 B (Neg)5V TTL0 to 5VCN1: 77I/O GG-SynchronizationRS485-ISO Adopter Data5V TTL0 to 5V8ENC A OUTEncoder A Output9ENC B OUTEncoder B Output110RS232 TxRS232 Transmit211RS232 RxRS232 Receive312+5Vdc OUT+5Vdc Supply Out413GNDSignal GNDFor -DE Option, Pin 15 is Contorl power (20V to 48V) andA1	5I/O ERS485 A (Pos)5V TTL0 to 5V6I/O FRS485 B (Neg)5V TTL0 to 5V7I/O GG-SynchronizationRS485-ISO Adopter Data5V TTL0 to 5V8ENC A OUTEncoder A Output5V TTL0 to 5VPIN #NAME9ENC B OUTEncoder B Output1I/O G2+5V dc OUT10RS232 TxRS232 Transmit2+5V dc OUT3RS232 Tx11RS232 RxRS232 Receive4RS232 Rx3RS232 Rx12+5Vdc OUT+5Vdc Supply Out5GND5GND14POWER GNDFor -DE Option, Pin 15 is Contorl power (20V to 48V) andA1DRIVE PWR	5 I/O E R5485 A (Pos) 5V TTL 0 to 5V 6 I/O F R5485 B (Neg) 5V TTL 0 to 5V 7 I/O G G-Synchronization R5485-ISO Adopter Data 5V TTL 0 to 5V 8 ENC A OUT Encoder A Output FUNCTIONS 9 ENC B OUT Encoder B Output FUNCTIONS 10 R5232 Tx R5232 Transmit FUNCTIONS 11 R5232 Rx R5232 Receive R5232 Rx R5232 Receive 13 GND Signal GND For -DE Option, Pin 15 is Contorl power (20V to 48V) and A1 DRIVE PWR Diruction	5 I/O E RS485 A (Pos) 5V TTL 0 to 5V 6 I/O F RS485 B (Neg) 5V TTL 0 to 5V 7 I/O G G-Synchronization RS485 I (Neg) 5V TTL 0 to 5V 7 I/O G G-Synchronization RS485-ISO Adopter Data 5V TTL 0 to 5V 8 ENC A OUT Encoder A Output FUNCTIONS Ties to CN2, PIN # 9 ENC B OUT Encoder B Output FUNCTIONS Ties to CN2, PIN # 10 RS232 Tx RS232 Transmit 1 I/O G G-Synchronization 7 12 +5Vdc OUT +5Vdc Supply Out For -DE Option, Pin 15 is Contorl power (20V to 48V) and A1 DRIVE PWR Dirve Power (20 - 48Vdc) 15^ 14 POWER GND POWER GND For -DE Option, Pin 15 is Contorl power (20V to 48V) and A1 DRIVE PWR Dirve Power (20 - 48Vdc) 15^

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